

# COLLABORATION WORKSHOP

## Overview

**Objective:** Develop a deep learning scheme for detecting defects in the LPBF process.

**Target:** Prediction of defects using thermal signatures and spatter counts obtained through cost-effective equipment.

**Purpose:** Enable in-situ defect prediction during manufacturing and repair of defects rescanning. Additionally, investigate via defect formation mechanisms through feature importance analysis.

### +95% True Positive Ratio on Test Set



## Data-driven Local Porosity Prediction in Laser Powder Bed Fusion via In-situ Monitoring Berkay Bostan (beb171@pitt.edu), Shawn Hinnebusch, David Anderson, and Albert C. To (albertto@pitt.edu)

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## In-Situ Defect Detection Using IR Imaging and Machine Learning









## NATIONAL TECHNOLOGY ABORATORY

#### **The Complex Part**



•P = 350 W •V = 1000 mm/s

Hatch distance = 0.168 mm Laver thickness = 0.08 mm Rotation = 67° No stripes

•Layer thickness = 0.08 mm Rotation = 67° No stripes LOF REGIME



**The Other Blocks** 

Standard EOS Parameters •P = 285 W •V = 960 mm/s Hatch distance = 0.11 mm Laver thickness = 0.04 mn Rotation = 67° 5 mm stripes

#### **Highly Unbalanced Dataset Problem Solution: Oversampling**



### Conclusions

- 95% of total pores could be predicted both in LOF and standard regime in the test set.
- The most crucial feature for porosity prediction is the spatter generation in both standard and LOF regimes.
  - Competing effects in standard regime
  - Denudation and larger melt pool prevents pore generation in LOF regime
- The cooling rate is the second most dominant feature.
  - While lower cooling rates fix the LOF pores, sometimes they may cause keyhole pore generation.





